

# **TCI-W-U Universal Controller**



#### Features

- Universal PID and/or binary control for any analog input/output signal and range
- Multiple auxiliary functions: heat-cool auto changeover, automatic enable, setpoint compensation
- Averaging, min. and max. functions
- Cascading of control loops (-W22 type)
- Alarm monitoring of low and high limits on all inputs
- Programmable reaction in case of alarm
- Feedback function for inputs and set points
- Functions for dehumidifying, set point shift, cascade control
- Password protected programmable user and control parameters

#### TCI-W22-U also includes

- Power Cap protected real-time clock with 48hr power backup
- 7-day programmable schedules, with options including change of setpoints and direct position of manual outputs
- Blue backlight

Fan, Pump control

#### Applications

- Fan coil units
- Heat exchangers
- Zoning

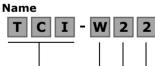
VAVAir handlers

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- Humidifiers Dehumidifiers Ventilation
- Radiant heating
- Radiant cooling
- Pressurization

## General

- TCI-W11-U: 1 independent control loop, 1 internal temperature sensor, 1 universal input (analog/binary/temp), 2 binary outputs, 1 analog output
- TCI-W22-U: 2 independent control loops, 1 internal temperature sensor, 2 universal inputs, 2 binary outputs, 1 analog output.
- Internal temperature sensor standard. Add replaceable humidity element as required: AES3-HT-A2 (2%), AES3-HT-A3 (3%), or AES3-HT-A5 (5%)
- Flexible application configuration is made with a parameter-setting routine using the standard operation terminal.





#### Ordering

Model	Stock code	Loop	Temperature Input	Humidity Input	Universal Input	Binary Output	Analog Output	Option
TCI-W11-U	40-10 0074	1	1	0	1	2	1	Standard
TCI-W11-U-H	40-10 0163	1	1	1	1	2	1	RH Sensor 3% acc.
TCI-W22-U	40-10 0076	2	1	0	2	2	1	Clock schedules
TCI-W22-U-H	40-10 0078	2	1	1	2	2	1	RH Sensor 3% acc.
AES3-HT-A2	40-50 0102			1				RH Sensor 2% acc.
AES3-HT-A3	40-50 0103			1				RH Sensor 3% acc.
AES3-HT-A5	40-50 0104			1				RH Sensor 5% acc.

**Temperature sensors**: Use Vector Controls NTC sensors to achieve maximum accuracy:SDB-Tn10-20 (duct), SRA-Tn10 (room), SDB-Tn10-20 + AMI-S10 as immersion sensor.

**Actuators**: Choose modulating actuators with an input signal type of 0-10 V DC or 4-20 mA (Min. and max. signal limitations may be set with parameters.3-pointpoint actuators with constant running time are recommended.

**Binary auxiliary devices** (e.g. pumps, fans, on/off valves, humidifiers, etc.): Do not directly connect devices that exceed specified limits in technical specifications – observe startup current on inductive loads.



# Technical specifications

# Important notice and safety advice

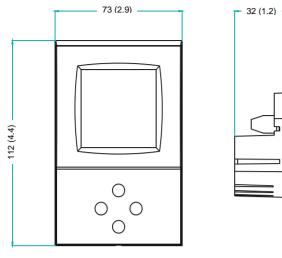
This device serves as a universal control device. It's not a safety device! If equipment failure endangers people's lives and/or property, it is the responsibility of the customer, installer and system integrator to add additional safety devices to prevent a system failure caused by such equipment failure. Failure to comply with specifications and local regulations may result in damage to equipment and endanger life and property. Tampering with the device and improper use will void the warranty.

Power Supply	Power Requirements	24V AC/DC ± 10%, 50/60 Hz, Class II, 48 VA max				
	Power Consumption	Max. 3 VA				
	Electrical Connection	Terminal Connectors 0.342.5 mm <sup>2</sup> wire (AWG 2412)				
	Clock backup	Min. 48 hours				
Signal inputs	Universal Input Input Signal Resolution Impedance	Setting for Voltage or Current 0–10 V or 0–20 mA 9.76 mV or 0.019 mA (10 bit) Voltage: 98kΩ Current: 240Ω				
	Universal Input	Input configured to remote temperature (RT) or digital input (DI)				
	Range Accuracy	NTC (Sxx-Tn10) 10kΩ, Type 2: -40100 °C (-0212 °F) -400 °C (-4032 °F): 0.5 K 050 °C (32122 °F): 0.2 K 50100 °C (122212 °F): 0.5 K > 100 °C (> 212 °F): 1 K				
	Humidity Sensor AES3-HT-Ax: Range Measuring Accuracy Hysteresis Repeatability Stability	Capacity sensor 0100 % RH See Figure to the right ± 1% ± 0.1% < 0.5% / year				
Signal outputs	Analog Output Output Signal Resolution Output Load	DC 0-10 V / 0-20 mA 9.76 mV / 0.019 mA Voltage: ≥1kΩ Current: ≤250Ω				
	Relays Outputs Type of disconnection AC Voltage DC Voltage	Micro-interruption 048 VAC, 2(1.2) A max. (Observe local regulation) 030 VDC, 2A max.				
	Insulation strength between relays contacts and system electronics: between neighboring contacts:	2000V AC to EN 60 730-1 1250V AC to EN 60 730-1				
Environment	Operation Climatic Conditions Temperature Humidity	To IEC 721-3-3 class 3 K5 050 °C (32122 °F) <95 % r.H. non-condensing				
	Transport & Storage Climatic Conditions Temperature Humidity Mechanical Conditions	To IEC 721-3-2 and IEC 721-3-1 class 3 K3 and class 1 K3 -2570 °C (-13158 °F) <95 % r.H. non-condensing class 2M2				
Standards	CE conformity EMC directive Low voltage directive	2014/30/EU 2014/35/EU				
	Product standards Automatic electrical controls for household and similar use Special requirement on temperature dependent controls	EN 60 730-1 EN 60 730-2-9				
	Degree of Protection	IP30 to EN 60 529				
	Pollution Class	II (EN 60 730-1)				
	Safety Class	III (IEC 60536)				
	Overvoltage Category	I (EN 60 730-1)				
General	Material: Cover, back part Mounting Plate	Fire proof ABS plastic (UL94 class V-0) Galvanized Steel				
	Dimensions (H x W x D)	Front part: 112 x 73 x 15 mm (4.4" x 2.9" x 0.6") Power case: ø 58 x 32 mm (ø 2.3" x 1.3")				
	Dimensions (H x W x D) RoHS compliant according to					



Connection

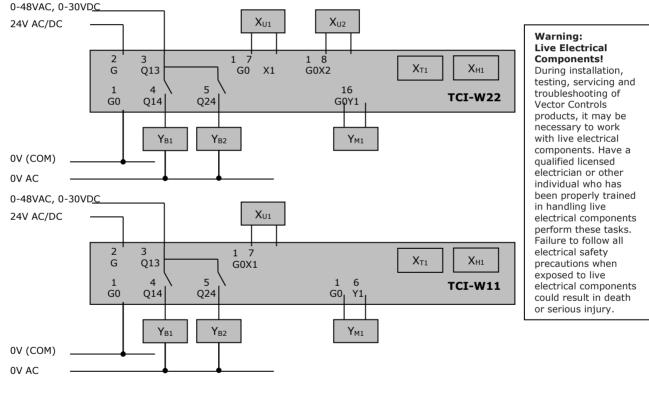
#### Dimensions, mm (inch)



#### Installation

15 (0.6)

- Install the controller on an easy accessible interior wall, approx. 1.5 m above the floor in an area of average temperature.
- Avoid direct sunlight or other heat sources, e.g. the area above radiators and heat emitting equipment.
- Avoid locations behind doors, outside walls and below or above air discharge grills and diffusers.
- Location of mounting is less critical if external temperature sensors are used.
- Ensure adequate air circulation to dissipate heat generated during operation.
- Observe local regulations.
   Do not mount in a wet or condensation prone environments.



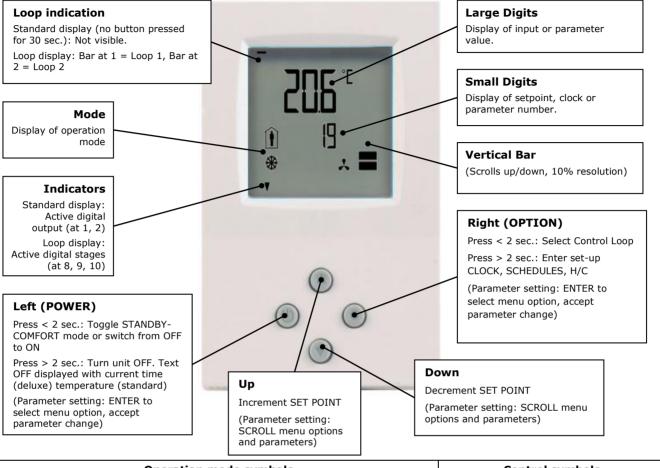
**Terminal Description** 

- **GO** Power supply: 0V, -24VDC; common for power supply, analog in- and outputs
- GPower supply:24VAC, +24VDCQBinary outputs:Potential free rel
  - Potential free relays contacts (see technical specification)
    - Yb1, b2 Binary output common
- XU1, u2 Universal input:
- NTC 10k $\Omega$  @ 25°C (77°F), 0...10 V or 0...20 mA (selectable by jumper) 0...10 V or 0...20 mA\*
- Ym1Analog output:0...10
- X<sub>T1</sub> Internal temperature input
- X<sub>H1</sub> Internal humidity input if AES3-HT is inserted

Use copper, twisted pair, conductors only. The operating voltage must comply with the requirements for safety extra-low voltage (SELV) as per EN 60 730. Use safety insulating transformers class II with double insulation as per EN 60 742; they must be designed for 100% ON-time. When using several transformers in one system, the connection terminal 1 must be galvanic connected. TCI is designed for operation of AC 24 V safety extra-low voltage and is short-circuit-proof. Supplying voltages above AC 24 V to low voltage connections may damage the controller or other devices. Connection to voltages exceeding 42 V endangers personnel safety.



# **Display and Operation**



	Operation mode symbols	Control symbols		
Î	Comfort (occupied): All control functions operating per set points	۲	Heating (Reverse) Active	
Ń	Economy (unoccupied): Set points shifted according to 1L07, 2L07	*	Cooling (Direct) Active	
OFF	Energy Hold Off: Outputs are off, inputs monitored for alarms	Θ	Schedule Set	
		•	Manual Override	

\*

Fan Active

# Standard display (Parameters UP08, UP09, UP10)

- Active when no key has been pressed for 30 seconds.
- Contents may be chosen with parameters.

# Loop display

Active when changing set points. Large digits show input value. Small digits show set point. Vertical bars show analog
output value. Arrows in position 1, 2 and/or 3 show active binary (digital) output stages

# Override of secondary set point in cascade control

- If cascade control is active, with variable air volume (VAV) for example, the user can override the primary loop and
  manually select the set point of the secondary loop-the loop is now changed to constant air volume (CAV). Typically for
  tuning the VAV system. This feature may be disabled with UP02.
- While the secondary loop is displayed change the set point with UP/DOWN. Override Cascade symbol appears.
- Press OPTION to move back to the temperature loop and cancel cascade override.



# **Power Failure**

- All parameters and set points are memorized and do not need to be re-entered.
- Upon return of power: Set *Parameter UP05* to keep the unit off, switch on, or operation mode before power failure.
- Clock and time schedule settings retained for 48 hours (after powered for at least 10 hours).

#### Error messages

- **Err1:** An assigned input is not enabled or missing. All control loops, functions and outputs tied to this input will be disabled. Verify input connections, jumper settings and parameter settings for the input involved.
- **Err3:** A function refers to a disabled input. Disable the function or enable the input.
- **Err4:** Internal failure. Product must be replaced.

# Manual heat – cool change

To manually change heating or cooling mode press the OPTION key for more than 2 seconds. Access to manual heat – cool change may be disabled with parameter UP03.

For TCI-W11-U: Press OPTION > 2 sec. SEL and H-C is displayed.	SEL
For TCI-W22-U: Press OPTION > 2 sec. SEL and current time is displayed. Press UP key twice. SEL and H-C is displayed. Press OPTION again to toggle H or C.	н-с 業 <b>券</b>

# Display input values

For TCI-W11-U: Press OPTION > 2 sec. SEL and H-C is displayed. Press UP key once: UI1 and its value are displayed For TCI-W22-U: Press OPTION > 2 sec. SEL and current time is shown. Press UP key three times. UI1 and value are displayed.	75% UI 1
Press UP key again to step through the next active input	
Note: disabled inputs will not be shown.	



# **Clock operation**

TCI-W22-Ucontains a quartz clock with battery back-up (not available in TCI-W11-U). Up to 8 mode changes based on time and day of the week may be programmed. Also position an output or select a set point directly with a time schedule. A blinking clock indicates that the time has not been sector that the unit has been without power for longer than 48 hours. The time needs to be set to allow time schedules to operate.

## **Clock setup**

clock setup		
Press OPTION > 2 sec. SEL and current time displayed	SEL	]
Press OPTION < 2 sec. to change time,	00:00	
Minutes blink: UP/DOWN to change, OPTION to save minutes,		
Hours blink: UP/DOWN to change, OPTION to save hour,	DAY1 (Mon)	
Press OPTION to save time,		
DAY1 blinks: UP/DOWN to change, OPTION to save day		]
Enable/disable time schedules		
Press OPTION $> 2$ sec. SEL and current time displayed	SEL	Pro
Press UP:	PRO	OFF/ON
SEL and PRO displayed, clock symbol blinks	•	
Press OPTION:	Ð	
Time schedule status displayed OFF or ON: Press OPTION		
OFF/ ON blinks, UP/DOWN to change, OPTION to save		
Creating time schedules Step 1: Select a switching time (Up to 8, Pr01–Pr08)		
Press UP while PRO-ON displayed: Large digits display Pr01, small digits display 00:00		Pr01
Press OPTION: 00:00 blinks		
Press UP/DOWN to select Pr01switching time from 00:00–23:45		08:00
Press OPTION to save switching time (bar appears indicating step 1 complete):		
DAY 1 blinks		
Step 2: Apply selected switching time (Pr01) to DAY1 (Mon) – DAY 7 (Sun)		•
While Pr01 is displayed and DAY1 is blinking:		Pr01
Press UP: Activate Pr01 switching time for DAY1 (triangle appears on 1)	DAY1	
Press DOWN:		DATI
Deactivate Pr01 switching time for DAY1(triangle disappears)		
Press OPTION to save Pr01 DAY1 (2 <sup>nd</sup> bar indicates step 2 complete):		
Repeat for DAY2 – DAY7		1234567
Step 3: Select action for switching time (Pr01+Days)		
After Pro1, DAY1-DAY7 is completed (Pro1 switching time activate or deactivate		Pr01
days), press OPTION again to come to desired action for Pro1. The following opt	tions appear in	no
order:		
No = switching time not active $OP = P = P = P = P = P = P = P = P = P =$		
OP = operation mode (select ON, OFF, COMFORT, ECONOMY) L1 = set point of loop 1 (select set point)		
L1 = set point of loop 1 (select set point) L2 = set point of loop 2 (select set point)		
d1 = ON/OFF status of do1 (output must be in manual mode)		
d2 = ON/OFF status of do2 (output must be in manual mode) d2 = ON/OFF status of do2 (output must be in manual mode)		
A1 = set point (0-100%) of ao1 (output must be in manual mode)		
After repeatedly pressing OPTION through DAY7:		
First available action No appears, blinking:		
Press UP/DOWN to scroll through the 8 possible actions (3 <sup>nd</sup> bar indicates step 3	3 complete)	
Step 4: Complete switching event (e.g. Pro1 = 08:00, DAY 1, Comfort mode)		
Available actions blink as you scroll through them, Press OPTION to select one:		Pr01
Characteristics of action (e.g. 0-100% for A1) appear (4 <sup>th</sup> bar indicates	s step 4	08:00
complete)		
Press UP/DOWN to select, OPTION to complete		



# Setting parameters to configure the controller

TCI is an intelligent controller with the flexibility to fit a wide range of applications. The control operation is defined by parameters set using the standard operation terminal. There are two levels:

- 1. User/display parameters (password 0009)
- 2. Control parameters (password 00241)

Recommended set-up procedure:

- 1. Set jumpers on the back of the controller for inputs and outputs
- 2. Connect power supply and inputs
- 3. Make sure Celsius Fahrenheit settings are correct (UP07)
- 4. Program input parameters
- 5. Program control parameters
- 6. Program output parameters
- 7. Program auxiliary functions and user settings
- 8. Test function of unit
- 9. Switch off power
- **10.** Connect outputs
- **11. Test control loop**

Parameters are grouped according to modules:

Module	Description	Notes	PW
UP	User and display parameters	Control user access and select display elements, regional settings	009
UI	Input configuration: 1T, 1H, 1U, 2U	TCI-W22-U: Internal temp. and RH, 2 universal inputs TCI-W11-U: Internaltemp.1 universal input	
LP	Control loops Lp1, Lp2	TCI-W22-U: 2 independent control loops TCI-W11-U: 1 independent control loop	
AO	Analog output configuration, AO1	TCI-W11-U and TCI-W22-U: 1 analog output	241
DO	Binary output configuration, do1, do2	TCI-W11-U and TCI-W22-U: 2 binary (digital) outputs - relays	
FU	Special functions	Common to all TCI	

#### How to change parameters

- 1. Press UP/DOWN buttons simultaneously for three seconds. The display will show firmware version and revision number. Press the OPTION button to start login.
- 2. CODE is shown in small display.
- 3. Code to access user parameters is 009, control parameter is 241. The access numbers are fixed and cannot be changed.
- 4. Select this using UP/DOWN buttons.
- 5. Press OPTION after selecting the correct code.
- 6. Once logged in with 009, the user/display parameters are displayed immediately. Once logged in with 241 control modules are displayed (Lp1, Lp2, 1u, 2u, etc.) –select with UP/DOWN and open with OPTION. As soon as the module is open its parameters are displayed.
- 7. Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the OPTION button. Three arrows are displayed to indicate that the parameter may be modified. Use UP/DOWN buttons to adjust the value.
- 8. After you are done, press OPTION to save the new value and return to the selection level (arrows disappear when selection is saved). Pressing left hand POWER button without pressing OPTION will discard the value and return without saving. For control parameters press POWER again to leave parameter selection and return to control module selection.
- 9. Press the POWER to leave the menu. The unit will return to normal operation if no button is pressed for more than 5 minutes



# User and display parameters (password 009)

Parameter	Description				Range	Default
UP 00	Enable access to	operation modes			ON/OFF	ON
UP 01	Enable access to set points					ON
UP 02	Enable manual co	Enable manual control in cascade				
UP 03	Enable change of	heating/cooling m	ode for 2 pipe sys	tems	ON/OFF	ON
UP 04	Enable access to	time programs:			ON/OFF	ON
UP 05	State after power 0= off, 1= on, 2=	r failure: = state before pow	er failure		0, 1, 2	2
UP 06	Shift the setpoint summer in order the POWER butto		ature in winter or conomy mode may rnal input (typical		ON/OFF	ON
UP 07	Celsius or Fahren	heit: ON= Fahrenh	neit, OFF= Celsius		ON/OFF	OFF (Celsius)
UP 08	Show standard d	isplay while no key	is pressed		ON/OFF	ON
	Select type of co	ntent for large digi	ts (00= OFF):			
UP 09	01= Input04= Binary Output02= Setpoint05= Clock03= Analog Output05= Clock			0-5	1	
	Select content source for large digits (0=OFF):					
UP 10	Input: 1= 1T 2=1H 3= 1U 4= 2U	Set point: 1= Lp1 2= Lp2	Analog output: 1 – AO1	Binary output: 1 - DO1 2 - DO2	0-4	1
UP 11		Select type of content for small digits (same options as UP09)				Standard = 2 Deluxe = 5
UP 12	Select content so	urce for small digit	s (same options a	s UP10)	0-4	1
	Select analog out	put for vertical bar	· display (00= OFF	F):		
UP 13	01= AO1 02= FO1	-	03= Output LP1 04= Output LP2		0-4	3
UP 14	Display heating/c	cooling state in star	ndard display mod	e	ON/OFF	OFF
UP 15		ON = Alarms blink after being active and need to be confirmed OFF= Alarms are only shown when they are active				ON
UP 16 (TCI-W22- U)	Clock display typ	ON/OFF	OFF (24hr)			
UP 17 (TCI-W22- U)	Reset timer for m 0= Not active 1-255= Delay fo COMFORT operat	0–255 Min	60(Min)			
UP 18 (TCI-W22- U)		switch on for 30 se witch on constantly			ON/OFF	OFF



# **Control configuration (Password 241)**

# Input configuration

#### Internal inputs 1T temperature and1H humidity (with added AES3-HT-A2, 3 or 5 element)

Para	meter	Description	Range	Default
1T00	1H00	Enable internal sensor	OFF/ON	ON
1T01	1H01	Display minimum value	-50-205	0
1T02	1H02	Display maximum value	-50-205	100
1T03	1H03	Sensor sampling rate (control speed decrease as rate increases)	0-100	10
1T04	1H04	Sensor calibration	per input	0
1T 05	1H05	Alarm 1low limit (1T), Alarm 3low limit (1H)	OFF/ON	OFF
1T06	1H06	Alarm 1/3low limit values	-40-215°C	5
1T07	1H07	Alarm 2high limit (1T), Alarm 4high limit (1H)	OFF/ON	OFF
1T08	1H08	Alarm 2/4high limit values	-40-215°C	50
1T09	1H09	Hysteresis Alarm 1, 2, 3, 4	0-100°	5
1T10	1H10	1H10 Calculate a range of inputs (0= not active): 1=average, 2=minimum, 3=maximum, 4=differential		0
Univers	al inputs	s 1U, 2U (TCI-W11-U: 1U only, TCI-W22-U: 1U and 2U)		
1U 00		type (0= not active): V or 0-20mA, 2=2-10V or 4-20mA, 3= passive temperature	0-3	1
1U 01	Display minimum value		-50-205	0
1U 02	Display maximum value		-50-05	100
1U 03	Analog	input display range: 0= x 0.01, 1= x 0.1, 2= x 1, 3 = x 10	0-3	1
1U 04	Analog	input unit of measure: 0= no unit, 1= %, 2= °C /°F, 3= Pa	0-3	0
1U 05	Sensor	sampling rate (control speed decrease as rate increases)	0-100	10
1U 06	Sensor	calibration	Per input	0
1U 07	Alarm 5	5low limit(1U), Alarm 7low limit (2U)	OFF/ON	OFF
1U 08	Alarm 5/7low limit value		-40-215°C	5°C(40°F)
1U 09	Alarm 6	Shigh limit (1U), Alarm 8 high limit (2U)	OFF/ON	OFF
1U 10	Alarm 6	5/8high limit value	-40-215°C	50°C(122°F)
1U 11	Hystere	sis alarm 5 and 6 (7 and 8)	0-100°	5°C(10°F)
1U 12		te a range of inputs (0=not active): rage, 2= minimum, 3= maximum, 4= differential	0-4	0

→ Set jumpers on the back of the controller: 0–10VDC (default), 0–20mA, or RT/DI (passive temperature or binary).

→ Further define analog inputs with U00.

- → Match sensor range to input display. With a differential pressure transmitter having 0-200 Pa measuring range set UO1 display minimum to 0 and UO2 display maximum to 200. The allowable range value of -50-205 may be adjusted with multipliers inUO3. The largest displayable values are -990-9999. Limiting range increases resolution. Applies to analog as well as passive temperature inputs.
- → For binary input (open/close contact) set the jumper to RT/DI and parameter U00 to an analog input. An open contact reads as a high value (100%), a closed contact as a low value (0%).
- → Enable / Disable an alarm. Setting the alarm enable to OFF will prevent the alarm from being displayed on screen. It may never the less be used to control an output by setting the appropriate output alarm flags. This way, an alarm limit may be used as interlock.
- → Specify the input value that triggers an alarm. Hysteresis is the difference between alarm level input and value required to turn the alarm off. An alarm is displayed as text if enabled (see table). Alarm text can be set to blink continuously until acknowledged by pressing the OPTION button or only while the alarm conditions are active (see user parameter UP15).

Input	1T	1H	1U	2U
Low limit	ALA1	ALA3	ALA5	ALA7
High limit	ALA2	ALA4	ALA6	ALA8

→ Calculate a range of inputs for loop control or display with T10, H10, and U12. The largest input of the group selected will carry the calculated value. When average is activated on 2U12 and 1T10, the averages carried on 2U. Inputs grouped for calculation must be of same type and range. It is possible to use different functions on different inputs. For example, minimum of 1T and 2U and maximum of 1U and 1H. It is not possible to use different functions on one input.



# Control loop configuration (TCI-W11-U: 1L only, TCI-W22-U: 1L and 2L)

Parameter	Description	Range	Default
1L 00	Select loop control input (0= loop disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2U	0-4	1
1L 01	Minimum set point limit heating	per input	10°C(50°F)
1L 02	Maximum set point limit heating	per input	28°C(82°F
1L 03	Minimum set point limit cooling	per input	18°C(64°F
1L 04	Maximum set point limit cooling	per input	34°C(92°F
1L 05	Enable set point compensation ( $0$ = disabled) 1= winter compensation, 2= summer compensation, 3= winter and summer	0-3	0
1L 06	Loop input special (0= normal): 1= combine loop 1 and loop 2 2= cascade with reverse sequence of primary loop 3= cascade with direct sequence primary loop 4= cascade with both reverse and direct sequence of primary loop	0-4	0
1L 07	Economy mode set point shift: (Function depends on 1L25) The comfort (occupied) setpoint is shifted by the value set with parameter. Reduces the heating set point and increases the cooling set point.	per input	5.0°C(10°F
1L 08	Dead zone between heating and cooling set points The Dead Zone Span lies between the heating and the cooling setpoint. The output is off while the measured value is within the dead zone span. A negative dead zone is not possible.	Per input	1.0°(2°F)
1L 25	Fixed setpoint in ECONOMY mode OFF = ECONOMY set point shift applies ON = In ECONOMY mode use minimum setpoint limit as setpoint in heating mode or maximum setpoint limit in cooling mode	ON, OFF	OFF
1L 26	Setpoint compensation range, the maximum range the setpoint is shifted. 0 = Temperature setback: the setpoint is shifted towards setpoint limit	Acc input	0.0°C

➔ Economy mode setpoints: There are two possibilities to change the setpoint in economy mode: Shift it by L07 or switch to the minimum setpoint limit in heating mode and maximum setpoint limit in cooling. Economy mode may be disabled by setting UP06 to OFF.

- → Control loops and sequences are activated when output parameters are defined.
- ➔ In cascade control (L06) the output of the primary loop determines the set point of the secondary loop. Select the cascade parameter on 2L to make 1L primary. Select the cascade parameter on 1L to make 2L primary. A typical application is a variable air volume system where the temperature output determines the pressure set point.

Cascade Control Example – VAV Application				
Secondary loop =airflow/pressure (2L)	Primary loop = temperature (1L)			
2L01=20%, 2L02=100%, 2L06=2	Temperature output is spanned between min (20%) and max (60%) pressure setpoint limits When temperature output is 50%pressure set point is 40% (e.g. 4v with 0- 10v rage)			
	temperature demand. Change the pressure range to change the impact the erature output will have on pressure setpoint			

#### → Setpoint Compensation

The setpoint compensation is typically used to compensate the set point due to a change in outside temperature. The relationship to the input used to drive the setpoint compensation is defined in auxiliary functions FU00 to FU07.

➔ Enable summer or winter set point compensation for this control loop with L05. Define the compensation range with L26.L26 defines the full setpoint shift once the compensation input has reached its lower limit in winter mode or upper limit in summer mode.

Setting the range parameter to 0 will activate the setpoint setback function: The setback function shifts the set point toward the set point minimum or the set point maximum based on an external input value. Once the compensation input has reached its lower limit in winter mode or upper limit in summer mode, the setpoint is fixed to the setpoint minimum or maximum value. Commonly this is used for humidity control to avoid condensation on outside walls or windows in very cold weather.



#### PI control sequence

Parameter	Description	Range	Default
1L 09	Offset for heating PI sequence	per input	0
1L 10	Offset for cooling PI sequence	per input	0
1L 11	P-band heating	per input	2.0°C(4.0°F)
1L 12	P-band cooling	per input	2.0°(4.0°F)
1L 13	Integral gain heating (0.1 steps) low= slow reaction, high= fast reaction	0-25.5	0.0
1L 14	Integral gain cooling (0.1 steps)	0-25.5	0.0
1L 15	Measuring interval integral (seconds) low= fast reaction, high value= slow reaction	0-255	1 sec.

## → Proportional control(P-band)

The proportional control function calculates the output based on the difference between setpoint and measured value. The proportional band (P-band) defines the difference between setpoint and measured value which will result in a 100% output. For example, with a heating or reverse 0-10v control sequence, and a 2.0°C (4.0°F) P-band value, at 10v the controller will be 2.0°C (4.0°F) below setpoint. This is the working range of the proportional control sequence.

Setting the proportional band to 0 disables proportional control.

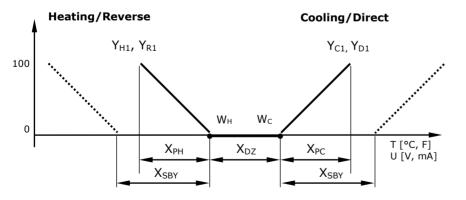
#### → Integral and Differential control

Proportional control is in most cases a very stable control mode. The flaw of proportional control alone, however, is that the setpoint is normally not reached. As the measured value gets closer to the setpoint, the output reduces until it reaches a point, a fraction above or below the setpoint, where the output equals the load. To reach the setpoint and achieve a higher level in comfort the Integral/Differential function should be activated.

**Integral Gain (KI)**dynamically increases the output by the selected KI value every **Measuring Interval TI** until the setpoint is reached. The challenge is to prevent hunting, where the output increases too fast, the temperature overshoots the setpoint, the output goes to 0, the temperature undershoots the setpoint, and the cycle repeats itself. Hunting may result if the integral gains too high or measuring interval too short. Each system is different. To prevent instability the P-band should be extended when integral gain is active (L14 or L15 set above 0).

Setting the integral gain to 0 disables integral and differential control.

Recommended Values						
heating (air) heating (radiant) humidifying cooling dehumidifying press					pressure	
P-band 2-3°C(4-6°F)		1-1.5°C(2-3°F)				
Measuring interval (TI)	2	5	15	1	70	1
Integral gain (KI)	0.2	0.1	0.1	0.2	0.3	0.8



#### Legend

Τ, U	Input signal temp/universal
X <sub>PH</sub>	P-band heating/direct
X <sub>PC</sub>	P-band cooling/reverse
$X_{DZ}$	Dead zone h/c set points
$X_{SBY}$	Economy mode set point shift
Wн	Set point heating/reverse
W <sub>C</sub>	Set point cooling/direct
$Y_{H1,}Y_{R1}$	PI sequence heating/reverse
$Y_{\text{C1},}Y_{\text{D1}}$	PI sequence cooling/direct



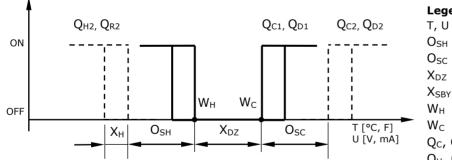
# **Digital control sequence**

Parameter	Description	Range	Default
1L 16	Action of stages: 0= cumulative: stage 1 stays on when 2 on comes on 1= single: stage 1 turns off when 2 on comes on 2= digital: stage 1 only, stage 2 only, then stage 1 plus 2	0-2	0
1L 17	Offset for heating/reverse binary sequences	per input	0.0°(0.0°F)
1L 18	Offset for cooling/direct binary sequences	per input	0.0°(0.0°F)
1L 19	Switching span heating	per input	1.0°(2.0°F)
1L 20	Switching span cooling	per input	1.0°(2.0°F)
1L 21	Switching hysteresis	per input	0.5°(1.0°F)
1L 22	Switching delay	0-255s	10s
1L 23	Activation of reverse/direct (heat/cool) sequence OFF= activates based on demand ON = follows heat/cool state of controller: Set manually or by auxiliary function (FU20-FU23)	ON/OFF	OFF
1L 24	Delay for heat /cool changeover when L23=OFF	0–255 min	5 min

→ Cumulative stage action (L16=0) is typically used in electric heat applications, and single stage action (L16=1) in fan speed applications. Digital stage action (L16=2) is especially useful in electric heat applications to generate three steps with just two outputs. For example: Step 1=100W, step 2=200W, step 3=300W.

	Cumulative	Single	Digital
Stage 1	Q1	Q1	Q1
Stage 2	$Q_1+Q_2$	Q <sub>2</sub>	Q2
Stage 3			$Q_1+Q_2$

- → Switching hysteresis (L21) is the difference between switching on and switching off. A small hysteresis will increase the number of switching cycles and thus the wear on associated equipment.
- → With switching delay (L22) cumulative stages will not switch on simultaneously. With a sudden demand or initial power stage 2 will not start earlier than 10 seconds (default value) after stage 1 has been initiated.



LegendT, UInput signal $O_{SH}$ Offset heating/direct $O_{SC}$ Offset cooling/reverse $X_{DZ}$ Dead zone $X_{SBY}$ Economy set point shift $W_H$ Set point heating/reverse $W_C$ Set point cooling/direct $Q_{C}$ ,  $Q_D$ Birary sequences cooling/direct

 $Q_{\text{H}},~Q_{\text{R}}\textsc{Binary}$  sequences heating/reverse



# **Output configuration**

## Analog output configuration (1A)

Parameter	Description	Range	Default
1A 00	Select control loop or special function (0= OFF): 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning or by time schedule (0-100%) 5 = Transmit value of an input	0-5	1
1A 01	When 1A00=1configure output: 0= Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) 3= Transmit setpoint When 1A00 = 4: Manual positioning or by time schedule	0-4	0
	0 = time schedule only 1 = manual positioning and by time schedule When 1A00=5, select input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2U		
1A 02	Type of output signal: OFF= 0-10V, 0-20mA, ON= 2-10V, 4-20mA	ON/OFF	OFF
1A 03	Minimum limitation of output signal default and in loop heating mode	0-100%	0
1A 04	Maximum limitation of output signal default and in loop heating mode	0-100%	100%
1A 05	Minimum limitation of output signal in loop cooling mode	0-100%	0%
1A 06	Maximum limitation of output signal in loop cooling mode	0-100%	100%
1A 07	Choose alarm to set output to 100% (output 0%on conflicting alarms) ママママママママ Alarm: 1 2 3 4 5 6 7 8	ALA1-ALA8	
1A 08	Choose alarm to set output to 0%. (output 0% on conflicting alarms) $\nabla \nabla \nabla \nabla \nabla \nabla \nabla \nabla \nabla$ Alarm: 1 2 3 4 5 6 7 8	ALA1-ALA8	
1A 09	Transmit value (1A00=5): minimum input value	per input	0°C
1A 10	Transmit value (1A00=5): maximum input value	per input	100°C

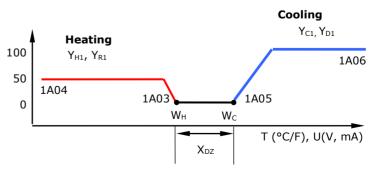
→ Set jumpers on the back of the controller: 0-10VDC (default), or 0-20mA.Further define analog outputs with A02.Custom ranges can be created by setting minimum and maximum signal limits.

→ A control loop, special function, digital control or analog control sequence is not active until it is assigned an output.

→ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. The required output for each alarm can be individually selected. Multiple alarms can be signed to one output. If one alarm is selected to simultaneously activate and deactivate an output, the one to de-activate has precedence.

## **Output Priority**

- 1. Alarm level low 2. Alarm level high
- 3. Operation mode OFF
- 4. Control function
- → With manual positioning (1A00=4) position the output by time schedule or directly in 0.5% steps. Setting 1A01 to 0 will disable manual positioning. The output will then only be controlled by time schedule.
- → With dehumidifying (1A00=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- → Input values of inputs and set points of control loops may be transmitted on the analog outputs.
- → For VAV Function individual minimum and maximum limits may be assigned for cooling and heating. In VAV applications maximum cooling output matches the maximum air volume the VAV box is set to deliver. As demand for airflow in cooling mode decreases, airflow dwindles until it reaches minimum cooling output (1A05). This minimum will be based on the airflow needed at design cooling and is typically 10% to 15% of maximum cooling airflow. When this minimum is reached the system is in dead-band – neither heating nor cooling. Minimum airflow in heating mode is set with 1A03. As the system moves into heating mode, heating airflow increases until it



reaches the maximum heating output (1A04), typically 30 to 50% of maximum cooling airflow.



# Digital output configuration (1d, 2D)

#### Floating point outputs (1d00 or 2D00=ON)

Parameter	Description	Range	Default
1d00	Enable digital or floating-point output OFF= 1dand 2D are two digital outputs ON = 1dand 2D are one floating point output (1d open,2D close)	ON/OFF	OFF
1d01	Select control loop or special function (0= OFF) 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning (open/close) 5 = Controller state functions	0-5	0
1d02	If1d01=1 configure output: 0=Heating/reverse 1= Cooling/direct 2= Heating and cooling (2 pipe) If 1d01 = 4 Manual positioning or time schedule controlled 0 = Time schedule controlled only 1 = Manual positioning and time schedule controlled If 1d01=5 select state functions: 0= ON if controller operation state is ON 1= ON while demand on any output 2= ON while controller in heating mode and operation state ON	0-5	0
	3= ON while controller in reacing mode and operation state ON 3= ON while controller in cooling mode and operation state ON		
1d03	Running time (from open to close)	0-255s	90s
1d04	Switching difference for floating point signal	0-100s	5s
1d05	Not used		
1d06	Choose alarm to set output to 100% (output 0% on conflicting alarms) $\bigtriangledown$ Alarm: 1 2 3 4 5 6 7 8	ALA1-ALA8	
1d07	Choose alarm to set output to 0% (output 0% on conflicting alarms) ∇∇∇∇∇∇∇ Alarm: 1 2 3 4 5 6 7 8	ALA1-ALA8	
1d08	Not used		
1d 09	Not used		

→ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. Each alarm's required output can be individually selected. Multiple alarms can be signed to one output. Should one alarm be simultaneously selected to activate and deactivate the output, the one to de-activate has precedence.

**Output Priority** 

1. Alarm level low

Alarm level high
 Operation mode OFF

4. Control function

- $\rightarrow$  With manual positioning (1d01=4) position the output directly (open/close).
- With dehumidifying (1d01=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- → For floating point outputs, the running time of the actuator used needs to be specified with 1d03. Running time is defined as the time required for the actuator to run from fully open to fully closed and vice versa. Actuators with a fixed running time are recommended. Once fully open or fully closed the running time for the actuator is extended for a full run-time cycle. This will allow the actuator position to be synchronized in case it has been moved during off time or an actuator with variable running time was used. Use switching difference parameter 1d04, to reduce the switching frequency of the actuator. The actuator will only move if the difference to the current actuator position is larger than this parameter.
- → State functions (1d01=5) activate the output based on certain conditions with or without a demand for heating or cooling, in either comfort or standby mode. In Energy Hold OFF mode (EHO) the output will be off.



## Digital outputs (1d00, 2D00=OFF)

Parameter	Description	Range	Default
1d01	Select control loop or special function (0= OFF) 1 = LP1, 2 = LP2 3 = Dehumidify (4 pipe, max LP1 cooling, LP2 direct) 4 = Manual positioning (on/off) 5 = State functions	0-5	0
1d02	When 1d01=1, configure output: 0= Stage 1 heating/reverse 1= Stage 1 cooling/direct 2= Stage 1 heating and cooling, reverse and direct 3= Stage 2 heating/reverse 4= Stage 2 cooling/direct 5= Stage 2 heating and cooling, reverse and direct When 1d01=5, select state functions: 0= ON if controller operation state is ON 1= ON while demand on any output 2= ON while controller in heating mode and operation state ON 3= ON while controller in cooling mode and operation state ON	0-5	0
1d03	Switch-off delay (time output active with no more demand) Delay is in seconds or minutes depending on d09	0-255	90sec
1d04	Switch-on delay (time demand active before output on) In state mode 1d01=5 outputs disabled during switch-on delay Delay is in seconds or minutes depending on d09	0-255	5 sec
1d05	Activate PWM, set cycle time, seconds (>0activates,0 deactivates)	0-1650s	0s
1d06	Choose alarm to set output to ON (output OFF on conflicting alarms) ママママママママ Alarm: 12345678	ALA1-ALA8	
1d07	Choose alarm to set output to OFF (output OFF on conflicting alarms) ママママママママ Alarm: 12345678	ALA1-ALA8	
1d08	Display fan symbol while active	ON/OFF	OFF
1d 09	Binary switching delays in minutes or seconds OFF = delays are in seconds, ON = delays are in minutes	ON, OFF	OFF

→ Low and high limit alarms are defined with input parameters. With output parameters assign an alarm to an output and select output state. Each alarm's required output can be individually selected. Multiple alarms can be signed to one output. Should one alarm be simultaneously selected to activate and deactivate the output, the one to de-activate has precedence.

Output Priority

1. Alarm level low

2. Alarm level high 3. Operation mode OFF

4. Control function

- $\rightarrow$  With manual positioning (1d01=4) position the output directly (ON/OFF).
- → With dehumidifying (1d01=3) the maximum value is taken of cooling and dehumidifying. When the humidity is too high, cooling will continue to operate, even without a demand for cooling, to dehumidify the air and heating will activate to maintain comfort.
- → State functions (1d01=5) activate the output based on certain conditions with or without a demand for heating or cooling, in either comfort or standby mode. In Energy Hold OFF mode (EHO) the output will be off.
- ➔ Pulse width modulation (PWM) mode is enabled with 1d05. In PWM mode the digital output will be switched on/off once per cycle. The on and off times are calculated according to the PI settings of the respective control sequence (see control loop Parameters L09–L15). TCI-W11-U and TCI-W22-U use relays for the digital outputs. It is not recommended to use cycle times below 100 seconds as the lifetime of the relays will be shortened with frequent switching. For PWM applications requiring cycle times below 100 seconds we recommend using TCI-W13 with TRIAC outputs.

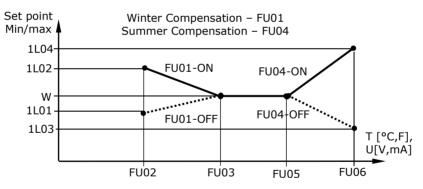


# **Auxiliary functions**

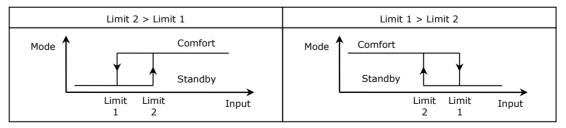
# Summer/winter compensation

Parameter	Description	Range	Default
Fu 00	Select compensation input (0= function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2U	0-4	0
Fu 01	Winter compensation setpoint setback OFF= shift toward control loop heating set point minimum ON= shift toward control loop heating set point maximum	ON/OFF	OFF
Fu 02	Winter compensation lower limit value – end shift	per input	5°C(41°F)
Fu 03	Winter compensation upper limit value – start shift	per input	20°C(68°F)
Fu 04	Summer compensation setpoint setback OFF= shift toward control loop cooling set point minimum ON= shift toward control loop cooling set point maximum	ON/OFF	ON
Fu 05	Summer compensation lower limit value – start shift	per input	35°C(95°F)
Fu 06	Summer compensation upper limit value – end shift	per input	40°C(104°F)
Fu 07	Show hot/cool symbol while compensation active	ON/OFF	OFF
Comfort/eco	nomy mode changeover		
Fu 08	Select comfort/economy changeover input (0= disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2U	0-4	0
Fu 09	Economy activation delay (seconds)	-1275s	300s
Fu 10	Input limit 1	per input	10
Fu 11	Input limit 2	Per input	90

→ Summer/winter compensation changes the set point due to a change in an input value, typically, but not limited to, an outdoor temperature input. Winter compensation starts when outside temperature drops below the upper limit of winter compensation (FU03). At maximum winter compensation the actual set point will be equal to the control loop's maximum heating set point (L02). Summer compensation starts when outside temperature exceeds the lower limit for summer compensation (FU05). At maximum summer compensation the actual set point will be equal to the control loop's maximum cooling set point (L04). Activatesummer/winter compensation with control loop configuration parameter(L05).



→ Use comfort/economy mode changeover with key card switches, occupancy sensors, etc. Set input limit 1 and 2 with possibilities below. Example: When Limit 2 is greater than Limit 1, switch comfort-to-economy at the lower value, economy-to-comfort at the higher value. Activate comfort/economy changeover with loop configuration parameter(L07).

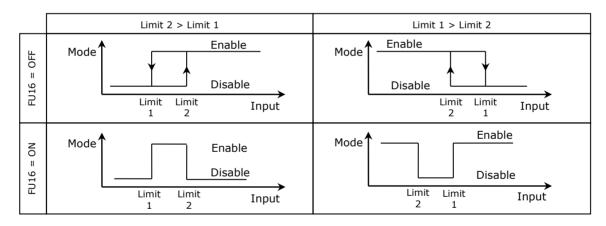




## Enable/disable

Parameter	Description	Range	Default
Fu 12	Select enable-disable input (0=function disabled): 1= 1T, 2= 1H, 3= 1U, 4= 2U	0-4	0
FU 13	Manual override permitted (without waiting for delay). This function allows starting the controller; even the enable conditions are not met. The controller will switch off again if the running conditions are not met until the disable delay is expired.	ON/OFF	OFF
Fu 14	Enable delay (seconds)	0-1275s	0
Fu 15	Disable delay (seconds)	0-1275s	300
Fu 16	Range of limits: OFF = When limit 2 is greater than limit 1, enable when input value is greater than limit 2, disable when input value is less than limit 1. When limit 2 is less than limit 1, enable when input value less than limit 1, disable when input value is greater than limit 2. ON = When limit 2 is greater than limit 1enable when input value is between limit 1 and limit 2. When limit 2 is less than limit 1, enable when input value below limit 2 or above limit 1	ON/OFF	OFF
Fu 17	Input limit 1	per input	10
Fu 18	Input limit 2	Per input	90
Fu 19	Disable in case of alarms	Selection	$\begin{array}{c} \bigtriangledown \bigtriangledown \bigtriangledown \lor $

→ Enable or disable the controller based on desired input values, such as high or low temperature, occupancy sensor, window contact, etc. Can be used as and function where several conditions must be met before disable or enable. Time schedules do not override, but manual override is permitted. Delay times may be assigned for both enable and disable (allows for the controller to start before validation of operation values takes place). Set input limit 1 and 2 with options below. Example: With FU16=OFF, and Limit 2 > Limit 1, switch enable-to-disable at Limit 1, disable-to-enable at Limit 2.



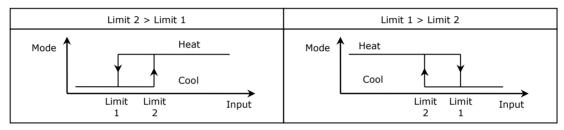


## Heating/cooling mode changeover

Parameter	Description	Range	Default
Fu 20	Select heat/cool changeover input (0=function disabled):	0-6	0
	1= 1T, 2= 1H, 3= 1U, 4= 2U, 5= h/c status loop 1, 6= h/c status loop 2		
Fu 21	Cooling activation delay (seconds)	0-1275s	300
Fu 22	Input limit 1	per input	20
Fu 23	Input limit 2	per input	40

→ Switch heating/cooling state based on a universal input value. The input may be from a supply media (air or water) or outdoor air temperature sensor. For supply media temperature we recommend switching to cooling at 16°C/61°F and to heating at 28°C/83°F. For outdoor temperature we recommend switching to cooling at 28°C/83°F and to heating at 16°C/61°F outdoor temperature. These recommendations are given as suggestions. The ideal settings may be different on the actual project depending on climatic and system conditions.

→ The change between heating and cooling is delayed to avoid unnecessary switching (FU21). Heat/cool status of one control loop may also be determined by the heat/cool state of the other loop (FU20= 5 or 6). The control loop used to determine the heat /cool state must be set to demand-based heating and cooling with (L23). Set limit 1 and limit 2 to switch between heating and cooling with options below. Example: When Limit 2 is greater than Limit 1, switch heat to cool at Limit 1, cool to heat at Limit 2. For binary open/close contact, open is a high value (100%), closed is a low value (0%).





Efficient use of energy for a better future

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